EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	463	(determin$ calculat$) near probabilit$ near (distribut$ histrobram)	US-PGPUB; USPAT	OR	ON	2006/03/06 09:18
L2	3	1 same global	US-PGPUB; USPAT	OR	ON	2006/03/06 09:07
L3	295	(determin$) near probabilit$ near (distribut$)	US-PGPUB; USPAT	OR	ON	2006/03/06 09:14
L4	0	3 and (global near state)	US-PGPUB; USPAT	OR	ON	2006/03/06 09:16
L5	4694	background near foreground	US-PGPUB; USPAT	OR	ON	2006/03/06 09:16
L6	1	1 and 5	US-PGPUB; USPAT	OR	ON	2006/03/06 09:19
L7	8797	(determin$ calculat$) same probabilit$ same (distribut$ histrobram)	US-PGPUB; USPAT	OR	ON	2006/03/06 09:19
L8	61	7 and 5	US-PGPUB; USPAT	OR	ON	2006/03/06 12:26
L9	3	"5471544".pn. "5355326".pn. "6701016".pn.	US-PGPUB; USPAT	OR	ON	2006/03/06 14:20
L10	3095	gupta.in.	US-PGPUB; USPAT	OR	ON	2006/03/06 14:22
L11	4	5 and 10	US-PGPUB; USPAT	OR	ON	2006/03/06 14:20
L12	227	gutta.in.	US-PGPUB; USPAT	OR	ON	2006/03/06 14:23
L13	6	5 and 12	US-PGPUB; USPAT	OR	ON	2006/03/06 14:56
L14	11055	(maximum global) near (probability likelihood)	US-PGPUB; USPAT	OR	ON	2006/03/06 14:57
L15	3264	(local individual pixel) near (probability likelihood)	US-PGPUB; USPAT	OR	ON	2006/03/06 15:01
L16	398	14 and 15	US-PGPUB; USPAT	OR	ON	2006/03/06 15:01
L17	15	5 and 16	US-PGPUB; USPAT	OR	ON	2006/03/06 15:01

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   Qian, R.J.; Sezan, M.I.;
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   Volume 4, 24-28 Oct. 1999 Page(s):143 - 146 vol.4
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2. **A Region-Level Motion-Based Background Modeling and Subtraction Using MRFs**
   Shih-Shinh Huang; Li-Chen Fu; Pei-Yung Hsiao;
   Robotics and Automation, 2005. Proceedings of the 2005 IEEE International Conference on
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3. **An algorithm for multiple object trajectory tracking**
   Mei Han; Wei Xu; Hai Tao; Yihong Gong;
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   Volume 1, 27 June-2 July 2004 Page(s):I-864 - I-871 Vol.1
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4. **Tracking humans using prior and learned representations of shape and appearance**
   Jongwoo Lim; Kriegman, D.;
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